

## PID CONTROLLER TUNING USING THE MAGNITUDE OPTIMUM CRITERION%0A

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Magnitude Optimum principle. Part II consists of Chaps. 3-6. In Chap. 3 the conventional tuning for the PID controller via the Magnitude Optimum criterion for type-I control loops is pre-sented. Advantages and drawbacks of this method are remarked and the revised PID control law is presented within the same chapter. The potential of the pro-

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The application of the Magnitude Optimum criterion for tuning the PID controller in the case of a known single input single output linear process model and regardless of its complexity shows

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tuning method is based on a magnitude optimum (MO) frequency criterion which makes the frequency response from set-point to plant output as close to one as possible [PID controller tuning using the magnitude optimum criterion](#)

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**On the Automatic Tuning of PID Type Controllers via the ...**

application of the Magnitude Optimum criterion for tuning the PID controller reveals an attractive feature of the method called 'the preservation of the shape of the step and frequency